

ViPS-FSL: Virtual-Patient Densification via Latent Space Co-Translation for Robust Few-Shot Cardiac MRI Segmentation

Mohamed Elbayumi^{1,2} and Mohammed S. M. Elbaz^{1*}

¹ Department of Radiology, Northwestern University, Chicago, IL, USA

² Department of Biomedical Engineering, Northwestern University, Chicago, IL, USA
mohammed.elbaz@northwestern.edu

Abstract. Few-shot cardiac MRI segmentation is often limited by support-set underutilization and reliance on unlabeled data, degrading performance on unseen domains and compromising the functional measurements (e.g., ejection fraction, chamber volumes) central to cardiac diagnosis. We propose ViPS-FSL, which reformulates few-shot segmentation as support-set densification: from a sparse, pathology-diverse support set, it builds a cross-pathology pairwise support graph with phase-aware edge typing to learn local image-mask co-translation models, then samples a graph-induced Perceptual Feature Space via volume-calibrated latent interpolation to decode fully labeled virtual patients. A segmentation model is then trained on the labeled support set augmented with these virtual patients, using no unlabeled data. We evaluate in two settings: in-distribution on a held-out same-domain ACDC test split, and out-of-distribution on the more challenging M&Ms cohort, unseen and spanning multiple vendors, centers, and pathologies. On held-out ACDC (N=50), ViPS-FSL ranks first at both 7 and 11 support subjects (88.5/89.0 average Dice), outperforming the strongest baseline by +2.6/+1.4 Dice with no unlabeled data. Under single-source transfer to the unseen M&Ms cohort (N=320), it outperforms five state-of-the-art baselines—each using 63/59 unlabeled subjects—reaching 87.4%/3.59 mm and 88.1%/3.29 mm (Dice/HD95), with per-chamber gains up to 5.5 Dice and 39% lower HD95 and generalizing across three unseen vendors despite single-vendor supervision. Thus, densifying labeled support—rather than relying on unlabeled data—yields strong, domain-robust few-shot segmentation. Code: <https://github.com/Elbaz-PIC-CVI-Lab/ViPS-FSL>.

Keywords: Cardiac MRI Segmentation · Support-Set Densification · Cross-Domain Generalization · Few-Shot Segmentation.

1 Introduction

Deep learning has transformed cardiac MRI segmentation, which underpins the quantitative functional measurements (e.g. ejection fraction or myocardial mass) that drive cardiac diagnosis and treatment planning [1]. Achieving this

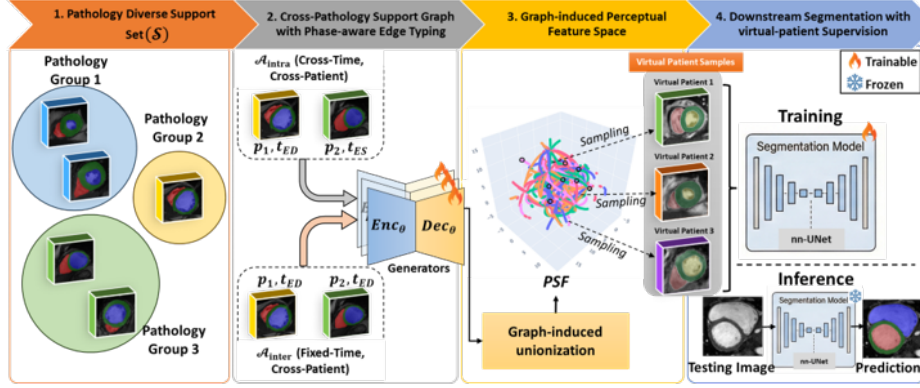


Fig. 1. Overview of the proposed ViPS-FSL framework.

reliably requires large, diverse annotated datasets that generalize across scanners, vendors, and populations [2, 3], yet expert annotation is costly. The problem is acute in cardiac MRI, where clinically meaningful variability is jointly shaped by pathology-dependent remodeling and cardiac phase [4], so sparse annotations rarely cover the relevant state space; this leads to segmentation performance degradation on unseen scanners or pathologies, and consequently inaccurate functional parameters that affect the diagnosis. Few-Shot Learning (FSL) has therefore emerged as a promising direction for low-label cardiac segmentation [5–7]. Existing FSL paradigms share recurring limitations: prototype/metric-based methods transfer class representations from a small support set [8–11], but struggle when sparse examples do not cover pathology-induced variation. Semi-supervised approaches improve low-label performance by leveraging unlabeled data [12–16], yet their gains depend on the source-domain unlabeled distribution and weaken under out-of-domain transfer. Recently, foundation-model distillation strategies show promise [17–19], but still require adaptation and do not model the coupled effects of remodeling and cardiac-phase dynamics. Collectively, these expose three bottlenecks: (B1) *support-set underutilization*, where sparse examples are treated as isolated templates; (B2) *unlabeled-data dependency*, where gains rely on unlabeled cohorts, introducing cohort-specific bias; and (B3) *cross-domain gap*, where models fail on unseen pathology–phase combinations in new datasets. These are amplified in cardiac MRI, where variability is jointly driven by cross-pathology remodeling and phase-dependent deformation.

Rather than relying on additional supervision, ViPS-FSL maximizes the utilization of the support set it already has: we decode labeled virtual patients from a learned feature space and treat them as augmentation samples that densify the labeled support set. This reframes few-shot segmentation as support-set densification—densification is the mechanism, improved single-source cross-domain segmentation the objective. From a pathology-diverse support set in which each phenotype contributes ED and ES states, ViPS-FSL builds a cross-pathology pairwise support graph with phase-aware edge typing—here “graph”

denotes pairwise support relations—and learns local image–mask co-translation models, one per edge $\times$ phase-pair. Their latent segments define a graph-induced Perceptual Feature Space (PFS), sampled via volume-calibrated interpolation to decode fully labeled virtual 3D image–mask pairs that augment the labeled support set, on which a segmentation network [2] is trained, using no unlabeled data.

Our contributions are: (1) a cross-pathology, phase-aware pairwise support graph with per-edge co-translation that converts sparse support into structured, labeled augmentation supervision; (2) a graph-induced PFS with volume-calibrated interpolation that densifies labeled support into a fully labeled virtual-patient cohort from support only; and (3) a strict two-setting evaluation — in-distribution (ACDC, $N=50$) where ViPS-FSL ranks first at two support-set sizes (7 and 11) using no unlabeled data, and single-source cross-domain transfer (ACDC [1] $\rightarrow$ M&Ms [23]) where it achieves the best segmentation with consistent gains across three unseen vendors.

2 Methods

2.1 Problem Formulation

Let $\mathcal{D} = \{s_i\}_{i=1}^N$ denote a cardiac MRI dataset of N subjects. Each subject:

$$s_i = (\{(x_i^t, y_i^t)\}_{t \in \mathcal{T}}, g_i) \quad (1)$$

where $x_i^t \in \mathbb{R}^{H \times W \times Z}$ is a 3D cardiac MRI volume at cardiac phase t , $y_i^t \in \{0, 1, \dots, C\}^{H \times W \times Z}$ is the corresponding multi-class segmentation mask with C anatomical classes, and g_i denotes the pathology/phenotype label (e.g., healthy, hypertrophic cardiomyopathy (HCM), dilated cardiomyopathy (DCM), myocardial infarction (MI)). The cardiac phase set $\mathcal{T} = \{\text{ED}, \text{ES}\}$, with ED and ES as end-diastole and end-systole.

In the few-shot learning (FSL) setting, a small, labeled support set:

$$\mathcal{S} = \{s_i\}_{i=1}^n \subset \mathcal{D}, \quad n \ll N \quad (2)$$

$\mathcal{S}$ is selected for training. The key challenge is that $\mathcal{S}$ sparsely samples the cardiac state space, which is jointly shaped by inter-subject anatomy, pathology-related remodeling, and phase-dependent deformation. This results in bottlenecks (B1–B3) mentioned in the introduction. ViPS-FSL addresses these bottlenecks by reformulating few-shot supervision as support-set densification. In our setting, $\mathcal{S}$ is chosen to be pathology-diverse (at least one representative per phenotype). We model a support-conditioned translator $\mathcal{G}$ that maps sparse labeled support to a dense virtual labeled cohort:

$$\mathcal{V} = \mathcal{G}(\mathcal{S}) = \{(\tilde{x}_k, \tilde{y}_k)\}_{k=1}^M \quad (3)$$

where $\mathcal{V}$ is a fully labeled virtual cohort constructed strictly from $\mathcal{S}$, with $\tilde{x}_k \in \mathbb{R}^{H \times W \times Z}$ the k -th 3D volume and $\tilde{y}_k \in \{0, 1, \dots, C\}^{H \times W \times Z}$ its multi-class mask. $\mathcal{V}$ covers intermediate pathology–phase states absent from $\mathcal{S}$. A full overview of the method is given in Fig. 1.

2.2 Cross-Pathology Support Graph with Phase-Aware Edge Typing

To operationalize $\mathcal{V} = \mathcal{G}(\mathcal{S})$, ViPS-FSL first constructs a non-redundant cross-phenotype, pathology-diverse pairwise support graph over $\mathcal{S}$ as $\mathcal{H}(\mathcal{S}) = (\mathcal{S}, \mathcal{E})$. Graph nodes represent labeled support subjects, while edges encode pairwise cross-subject relations as local latent traversal paths. Phase-aware edge typing captures temporal dynamics, and cross-pathology coupling is established through pairings of distinct patient phenotypes. We define the set of unordered support-subject pairs as:

$$\mathcal{P}(\mathcal{S}) = \{ (i, j) \mid 1 \leq i < j \leq n \} \quad (4)$$

which avoids redundant reverse instantiations (i.e., (i, j) and (j, i) are not treated as separate pair instances). Hence, $|\mathcal{P}(\mathcal{S})| = \binom{n}{2}$. For each pair $(i, j) \in \mathcal{P}(\mathcal{S})$, let $a, b \in \mathcal{T}$ denote source and target phases. We define two phase-pair edge-type sets:

$$\mathcal{A}_{\text{intra}} = \{ (a, b) \in \mathcal{T} \times \mathcal{T} \mid a = b \} = \{ (\text{ED}, \text{ED}), (\text{ES}, \text{ES}) \} \quad (5)$$

$$\mathcal{A}_{\text{inter}} = \{ (a, b) \in \mathcal{T} \times \mathcal{T} \mid a \neq b \} = \{ (\text{ED}, \text{ES}), (\text{ES}, \text{ED}) \} \quad (6)$$

While $\mathcal{A}_{\text{intra}}$ preserves cardiac phase, modeling cross-subject/cross-pathology variation, $\mathcal{A}_{\text{inter}}$ jointly models cross-subject/cross-pathology variation with phase-dependent deformation/remodeling. Thus, subject pairing controls cross-pathology traversal, while phase-aware edge typing controls how each pair is traversed in latent space.

2.3 Graph-Indexed Local Co-Translation Models

Rather than learning a single global translator, ViPS-FSL learns a set of local pairwise co-translation models indexed by graph edges:

$$\mathcal{F} = \{ F_{ij}^{a \leftrightarrow b} \mid (i, j) \in \mathcal{P}(\mathcal{S}), (a, b) \in \mathcal{A}_{\text{intra}} \cup \mathcal{A}_{\text{inter}} \} \quad (7)$$

Each local bidirectional model $F_{ij}^{a \leftrightarrow b}$ is trained on labeled state pairs $(x_i^a, y_i^a) \leftrightarrow (x_j^b, y_j^b)$, enabling both forward and reverse traversals within a single model and yielding a piecewise latent representation of the support-induced cardiac state space. To preserve image-label coupling, translation is performed jointly in concatenated image-mask space; given $(x_{\text{src}}, y_{\text{src}})$ and $(x_{\text{tgt}}, y_{\text{tgt}})$, each local model uses a 3D CNN encoder-decoder generator that maps a source state to a translated image-mask pair $(x_{\text{gen}}, y_{\text{gen}}) = G_{\theta_{ij}}^{(a,b)}(x_{\text{src}}, y_{\text{src}})$. A parallel 3D Vision-Transformer registration network $R_{\psi_{ij}}^{(a,b)}$, adopted from [20], predicts a deformation field ϕ between the generated and the target samples:

$$\phi = R_{\psi_{ij}}^{(a,b)}((x_{\text{gen}}, y_{\text{gen}}), (x_{\text{tgt}}, y_{\text{tgt}})) \quad (8)$$

This co-translation pairs appearance and label changes, optimizing each model by:

$$\mathcal{L}_{\text{local}} = \lambda_{\text{reg}} \mathcal{L}_{\text{reg}} + \lambda_{\text{fid}} \mathcal{L}_{\text{fid}} + \lambda_{\text{mask}} \mathcal{L}_{\text{mask}} \quad (9)$$

The registration loss enforces alignment with the target and smooth deformation:

$$\mathcal{L}_{\text{reg}} = \mathcal{L}_{\text{corr}}((x_{\text{gen}} \circ \phi, y_{\text{gen}} \circ \phi), (x_{\text{tgt}}, y_{\text{tgt}})) + \lambda_{\text{sm}} \|\nabla \phi\|_2^2 \quad (10)$$

where $\mathcal{L}_{\text{corr}}$ is an L_1 -based correction term jointly applied to image and mask channels. To stabilize translation, the image fidelity loss combines Learned Perceptual Image Patch Similarity (LPIPS) [21] and Structural Similarity Index Measure (SSIM):

$$\mathcal{L}_{\text{fid}} = \lambda_{\text{LPIPS}} \text{LPIPS}(x_{\text{gen}}, x_{\text{tgt}}) + \lambda_{\text{SSIM}} (1 - \text{SSIM}(x_{\text{gen}}, x_{\text{tgt}})) \quad (11)$$

To preserve anatomical label structure, we use a class-weighted mask consistency loss:

$$\mathcal{L}_{\text{mask}} = \sum_{c=1}^C \omega_c \left(\mathcal{L}_{\text{GDice}}^{(c)} + \lambda_{\text{mSSIM}} \mathcal{L}_{\text{SSIM}}^{(c)} + \lambda_{\text{NCC}} \mathcal{L}_{\text{NCC}}^{(c)} \right) \quad (12)$$

with GDice as generalized Dice loss and NCC as normalized cross-correlation.

2.4 Perceptual Feature Space and Virtual Cohort Construction

We define the Perceptual Feature Space (PFS) as the union of latent segments induced by all local co-translation models over the cross-pathology support graph:

$$\mathcal{M}_{\text{PFS}} = \bigcup_{(i,j) \in \mathcal{P}(\mathcal{S})} \bigcup_{(a,b) \in \mathcal{A}_{\text{intra}} \cup \mathcal{A}_{\text{inter}}} \Gamma_{ij}^{a,b} \quad (13)$$

where $\Gamma_{ij}^{a,b}$ denotes the latent segment connecting support states (x_i^a, y_i^a) and (x_j^b, y_j^b) under the local model $F_{ij}^{a \leftrightarrow b}$. Crucially, $\mathcal{M}_{\text{PFS}}$ is not a separate global network; it is the graph-induced union of local latent segments learned from $\mathcal{S}$. Operationally, ViPS-FSL uses $\mathcal{M}_{\text{PFS}}$ as the sampling domain for virtual cohort decoding:

$$\mathcal{V} = \mathcal{G}(\mathcal{S}) = \text{Decode}(\text{Sample}(\mathcal{M}_{\text{PFS}})) \quad (14)$$

where $\text{Sample}(\mathcal{M}_{\text{PFS}})$ denotes graph-edge selection plus latent interpolation along a selected segment $\Gamma_{ij}^{a,b}$. To sample from $\mathcal{M}_{\text{PFS}}$, we first select a graph-indexed latent segment $\Gamma_{ij}^{a,b} \subset \mathcal{M}_{\text{PFS}}$. The corresponding source and target states are encoded as $z_{\text{src}} = \text{Enc}_{\theta_{ij}}^{(a,b)}(x_{\text{src}}, y_{\text{src}})$ and $z_{\text{tgt}} = \text{Enc}_{\theta_{ij}}^{(a,b)}(x_{\text{tgt}}, y_{\text{tgt}})$. An initial latent trajectory is generated by spherical linear interpolation (SLERP) [22]:

$$z_k = \text{SLERP}(z_{\text{src}}, z_{\text{tgt}}; \omega_k), \quad \omega_k \in [0, 1] \quad (15)$$

As SLERP weights do not ensure uniform anatomical variation, we calibrate interpolation by computing mask-derived volumes and fit a B-spline to map ω_k to volume, yielding calibrated weights ω_k^* with quasi-uniform volume change along the latent path. This constrains interpolated states to follow a physiologically plausible volume trajectory between the ED and ES anchors, rather than arbitrary appearance blending:

$$z_k^* = \text{SLERP}(z_{\text{src}}, z_{\text{tgt}}; \omega_k^*) \quad (16)$$

The calibrated codes are decoded into virtual image-mask pairs; aggregating the local subsets over all edges and phase-pair types forms the full cohort $\mathcal{V} = \mathcal{G}(\mathcal{S})$ (Eq. 3). Because decoding is joint in image-mask space, every sample is labeled and couples cross-pathology variation with phase dynamics. The segmentation network (nnU-Net [2]) is trained on the labeled support augmented with $\mathcal{V}$, using no unlabeled data, pseudo-labeling, or query-time adaptation; the real support $\mathcal{S}$ also fits the co-translation models and defines the PFS. This addresses (B1) via graph-based densification, (B2) by relying solely on labeled support ($\mathcal{V} = \mathcal{G}(\mathcal{S})$), no unlabeled data), and (B3) by dense sampling of intermediate pathology-phase states absent from $\mathcal{S}$.

3 Experiments and Results

Datasets. We use ACDC [1] (100 subjects: healthy controls plus four pathology groups) and M&Ms [23] (320 subjects; multi-center, multi-vendor, multi-pathology). Support sets of 7 and 11 subjects are drawn from the 70-subject ACDC training split, stratified across pathologies (≥ 1 per pathology, each contributing ED and ES). We evaluate in-distribution on a disjoint ACDC test split (N=50) and out-of-distribution on the full unseen M&Ms dataset (320 subjects). The single-source cross-domain protocol follows established single-source domain-generalization practice in cardiac MRI [24].

Strict Evaluation Protocol. For a strictly one-to-one comparison, ViPS-FSL and all five baselines are trained and evaluated on identical data. All methods use the same support-set and cross-validation patients following [12] under our same preprocessing (cropping, normalization), and all baselines are re-trained from scratch. All baselines additionally consume 63/59 unlabeled ACDC subjects, whereas ViPS-FSL uses none.

Implementation Details. We resampled all data to 1.5×1.5 mm and center-cropped to $256 \times 256 \times 16$. Co-translation models were trained on all support-graph and phase pairs (1000 epochs, Adam, lr= $1e-4$); $\lambda_{\text{reg}}, \lambda_{\text{fid}} = 1$, $\lambda_{\text{mask}} = 20$, $\lambda_{\text{sm}} = 40$, $\lambda_{\text{LPIPS}} = 1$, $\lambda_{\text{SSIM}} = 10$, $\lambda_{\text{mSSIM}} = 1$, $\lambda_{\text{NCC}} = 10$ (Eq. 9–12). Volume-calibrated SLERP (200 steps/segment) yielded 4/6.4k labeled 3D samples for the 7/11 regimes, decoded into cohort $\mathcal{V}$; an nnU-Net [2] was trained on the augmented support set (200 epochs). Models are independent and trained in parallel (~ 10 min on one H100); the 11-subject regime uses 220 models (~ 37 GPU-h), ~ 4 GPU-h for decoding and nnU-Net training.

Virtual-Cohort Distribution Fidelity. As the densified intermediate states have no paired ground truth, we validate fidelity at the distribution level: for each method (stochastic elastic augmentation, a vanilla GAN, and our cohort) we generated 10K 2D samples from the same 11 subjects and compared them to a held-out ACDC split (N=50) via KID [25]. Against the floor (real support, 0.023), our virtual patients reach 0.207: $4 \times$ closer (better) than elastic augmentation and $9 \times$ closer than the GAN (Table 1). ViPS-FSL yields faithful samples (Supplementary Fig. A); decoded samples (Fig. 2) interpolate smoothly between real endpoints.

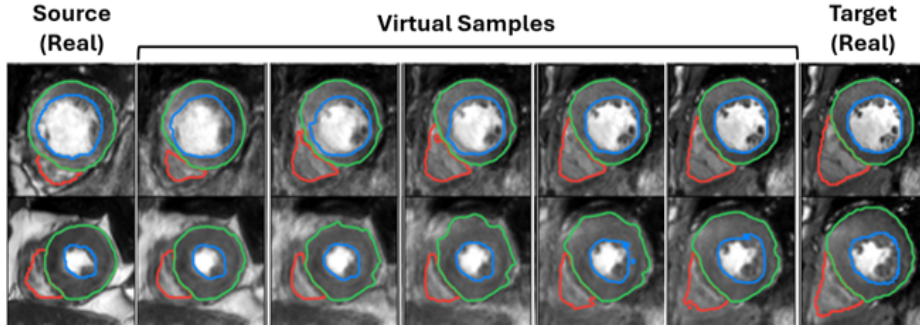


Fig. 2. Virtual patient samples. Top: cross-phase ED→ES ($\mathcal{A}_{\text{inter}}$); bottom: fixed-phase ($\mathcal{A}_{\text{intra}}$).

Table 1. Virtual cohort fidelity compared to unseen ACDC split (N=50).

Method	Reference Distribution	KID ($\downarrow$)
Standard Augmentation (+Elastic Deform.)	Unseen ACDC (N=50)	0.887 $\pm$ 0.008
GAN (trained on 11 subjects)		1.825 $\pm$ 0.006
ViPS-FSL (Virtual Patients Cohort)		0.207$\pm$0.006
Support set (11 subjects) – Baseline		0.023 $\pm$ 0.001

Table 2. In-distribution results on ACDC test split (N=50), for the 7/11-label regimes. Best per column in bold.

Method	Type	7-label regime		11-label regime	
		Dice (%) $\uparrow$	HD95 (mm) $\downarrow$	Dice (%) $\uparrow$	HD95 (mm) $\downarrow$
nnU-Net	Fully-sup. Baseline	45.6	23.6	49.9	20.6
SS-Net [13]	Consistency	79.8	8.5	83.3	6.6
MC-Net [14]	Self-train	80.0	8.4	83.9	6.4
BCP [12]	Consistency + Self-train	84.5	5.9	84.7	5.9
PPC [11]	Prototype	85.1	6.2	86.6	5.0
KnowSAM [17]	SAM distillation	85.9	6.8	87.6	4.2
ViPS-FSL (Ours)	Virtual-patients	88.5	4.8	89.0	4.3

In-Distribution Performance. On held-out unseen ACDC test (N=50), ViPS-FSL ranks first at both 7 and 11 support subjects with 88.5 and 89.0 average Dice, respectively, surpassing the strongest baseline by +2.6/+1.4 Dice, despite using no unlabeled data, while all baselines consume an additional 63/59 unlabeled subjects from the ACDC train split (Table 2).

Cross-Domain Generalization. We report strict single-source cross-domain performance on M&Ms in Table 3, comparing ViPS-FSL against five state-of-the-art FSL segmentation baselines (SS-Net [13], MC-Net [14], BCP [12], PPC [11], and KnowSAM [17]) spanning consistency regularization, self-training, and foundation-model distillation paradigms. All baselines use the remaining ACDC subjects as unlabeled streams (63/59); ViPS-FSL uses none, relying only on labeled support and the densified cohort. It attains the best overall Dice

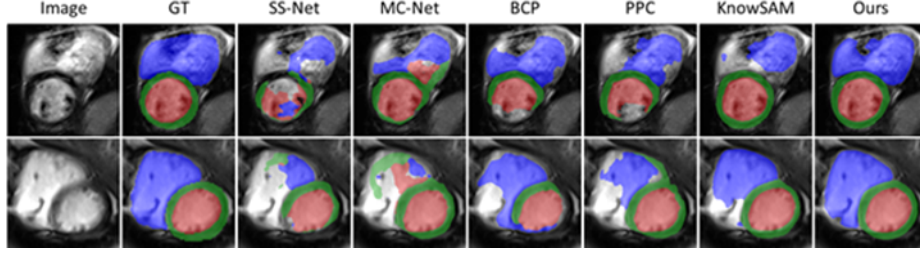


Fig. 3. Qualitative segmentation results. Our method vs. SOTA methods on M&Ms.

Table 3. Cross-domain comparison (M&Ms) using 7- and 11-label schemes. Method types: Consistency (Con.), Self-train (ST.), SAM distillation (SAM-KD), Virtual-patients (VP). Best per column in bold.

Method	Type	#Subj. (ACDC)		Dice (%) $\uparrow$				HD95 (mm) $\downarrow$			
		lab.	unlab.	RV	Myo	LV	Avg	RV	Myo	LV	Avg
nnU-Net	Full-Sup.	7	0	34.0	31.9	54.4	40.1	27.83	23.12	28.84	26.60
nnU-Net		11	0	46.5	25.9	53.6	42.0	27.06	23.21	25.84	25.37
SS-Net [13]	Con.		63	72.8	72.6	86.6	77.3	11.42	6.88	5.55	7.95
MC-Net [14]	ST.		63	73.1	77.0	88.8	79.6	11.45	5.10	4.61	7.05
BCP [12]	Con.+ST.	7	63	77.5	76.1	90.3	81.3	9.93	5.62	3.59	6.38
PPC [11]	Proto.		63	83.1	78.8	90.3	84.1	6.97	4.02	3.40	4.80
KnowSAM [17]	SAM-KD		63	82.2	82.7	90.6	85.2	8.90	3.11	3.90	5.30
ViPS-FSL (Ours)	VP		0	87.7	83.7	90.9	87.4	5.34	2.50	2.93	3.59
SS-Net [13]	Con.		59	74.2	76.1	86.7	79.0	11.40	5.27	6.16	7.61
MC-Net [14]	ST.		59	75.9	79.2	89.1	81.4	10.11	4.27	4.44	6.27
BCP [12]	Con.+ST.	11	59	79.2	74.8	89.0	81.0	9.89	6.02	4.30	6.74
PPC [11]	Proto.		59	83.1	80.8	91.1	85.0	7.69	3.60	3.05	4.78
KnowSAM [17]	SAM-KD		59	84.0	83.6	91.3	86.3	7.64	2.95	3.62	4.74
ViPS-FSL (Ours)	VP		0	88.9	84.1	91.3	88.1	4.65	2.43	2.79	3.29

and HD95 in both regimes: versus the best-performing baseline per-chamber, +5.5/1.0/0.3 Dice (RV/Myo/LV) with 23/20/14% lower HD95 at 7 labels, and +4.9/0.5 Dice (RV/Myo; LV matched) with 39/18/9% lower HD95 at 11 labels. Qualitative comparison (Fig. 3) further highlights ViPS-FSL’s cleaner chamber boundaries than the baselines under shift.

Cross-Vendor Generalization. To assess per-vendor generalizability, we report single-source cross-domain results on M&Ms split by vendor—Siemens (A), Philips (B), GE (C), Canon (D). ViPS-FSL achieves the best Dice and lowest HD95 on every vendor: +4/2/2/1 Dice points and 32/28/20/14% lower HD95 at 7 labels, and +3/1/2/2 points with 34/28/16/17% lower HD95 at 11 labels, versus the strongest per-vendor baseline. Despite Siemens-only support (ACDC), it generalizes robustly to the unseen vendors (Philips/GE/Canon).

Ablation Study. We studied different phase-aware edge types (Table 5): intra-phase edges densify within-phase neighborhoods, while inter-phase edges span ED–ES variation. Combining both gives the best Dice and HD95 at 7 labels and

Table 4. Per-vendor cross-domain generalization on M&Ms. Best per column in bold.

Method	#labels	Dice (%) $\uparrow$				HD95 (mm) $\downarrow$			
		A	B	C	D	A	B	C	D
SS-Net [13]	7	74	80	81	73	8.9	6.9	6.2	10.4
MC-Net [14]		75	83	82	78	8.6	5.8	5.9	8.3
BCP [12]		80	83	84	76	6.6	5.3	4.7	10.3
PPC [11]		82	86	86	82	5.6	4.0	4.1	6.0
KnowSAM [17]		82	87	86	86	6.6	4.6	4.8	5.1
Ours		86	89	88	87	3.8	2.9	3.3	4.4
SS-Net [13]	11	76	81	82	73	8.9	6.9	6.2	10.4
MC-Net [14]		79	83	84	80	7.4	5.5	5.1	7.3
BCP [12]		79	83	84	76	7.3	5.7	4.5	10.5
PPC [11]		83	87	86	83	5.6	3.9	3.8	6.4
KnowSAM [17]		84	88	87	86	5.7	4.0	4.7	4.8
Ours		87	89	89	88	3.7	2.8	3.2	4.0

Table 5. Ablation for phase-aware edge typing schemes. Best per column in bold.

Intra	Inter	#labels	Dice (%) $\uparrow$	HD95 (mm) $\downarrow$
$\checkmark$		7	87.08	3.870
	$\checkmark$		87.20	3.911
$\checkmark$	$\checkmark$		87.50	3.593
$\checkmark$		11	88.03	3.401
	$\checkmark$		88.15	3.318
$\checkmark$	$\checkmark$		88.15	3.295

the best HD95 at 11 labels, confirming that the two edge types are complementary, especially in low-data regimes.

4 Conclusions

We presented ViPS-FSL, which reframes few-shot cardiac segmentation as support-set densification: instead of relying on unlabeled data, it decodes a fully labeled virtual-patient cohort from a graph-induced feature space to augment the support set. This tackles support-set underutilization, unlabeled-data dependency, and the cross-domain gap. Results show that ViPS-FSL ranks first for in-distribution segmentation and, transferring from single-source supervision to the unseen multi-vendor M&Ms cohort, outperforms five baselines that all rely on unlabeled data. In conclusion, densifying the labeled support is an effective route to domain-robust few-shot cardiac segmentation. We plan to apply the method to other datasets and modalities.

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