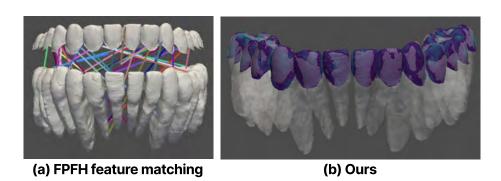
## Supplementary Materials



**Fig. 1.** (a) Registration by FPFH feature matching [?] which fails to achieve precise feature matching. The lines between meshes represent each matched FPFH feature between IOS and CBCT. A large number of IOS crowns are incorrectly matched with the CBCT counterparts. (b) Registration result from our method on the same patient.

## Algorithm 1 Mesh Removal

```
1: function MeshRemoval(IOS, CBCT, numTeeth, N, K, x)
2:
         \mathbf{for}\ i \leftarrow 1\ \mathbf{to}\ \mathrm{numTeeth}\ \mathbf{do}
 3:
             IOS_i \leftarrow Boundary PCD of IOS tooth number i
             IOS_i \leftarrow Aligning IOS_i in one direction
 4:
             CBCT_i \leftarrow Nearest point of CBCT matched to each point in <math>IOS_i
 5:
             for p \leftarrow 0 to len(CBCT<sub>i</sub>) do
 6:
 7:
                  \text{CBCT}_i^p \leftarrow \text{each PCD of CBCT}_i
 8:
                  if p == len(CBCT_i) then
                      \textbf{PointsInPath} \leftarrow \textbf{Dijkstra}(\textbf{CBCT}_i^p, \textbf{CBCT}_i^0)
                                                                                 ▶ Return all points on
9:
     the shortest path between CBCT_i^p, CBCT_i^0
                  else
10:
                       PointsInPath \leftarrow Dijkstra(CBCT<sub>i</sub><sup>p</sup>, CBCT<sub>i</sub><sup>p+1</sup>)
11:
                  CBCT_i \leftarrow Remove(CBCT_i, PointsInPath) \triangleright Remove points in <math>CBCT_i
12:
             LargestCBCT_i \leftarrow Largest(CBCT_i)
                                                                   ▷ Removing points may split the
    mesh into multiple segments; the largest segment is most likely the root section.
         return array of LargestCBCT<sub>i</sub>
14:
```