Physical-priors-guided Aortic Dissection Detection using Non-Contrast-Enhanced CT images (Supplementary)

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1 The way physical information is combined with Unet

Our method was inspired by the way U-Net combines with timestep t in the diffusion model. In our approach, at each layer of the U-Net, we assume the shape of the image data is [batch, channel, depth, height, width], and the shape of the physical information data is [batch, 3]. We reshape the image data to [batch, channel, depth \times height \times width] and the physical information parameters to [batch, 1, 3]. Then we perform cross-attention where Q is the physical information data, and K and V are the image data. This enhances the model's ability to distinguish based on specific physical information.

2 Model Optimization Algorithm

2 Z. Ding et al.

Algorithm 1 Detailed Model Optimization Flow

Require: x: Input NCE-CT image; t: Output from transformer encoder; y_1 : Real CE-CT image; y_2 : Real segmentation image; \tilde{y}_1 : Predicted CE-CT image; \tilde{y}_2 : Predicted segmentation image; α : Learning rate; β_1, β_2 : Adam optimizer parameters; λ_C : Classifier loss weight; λ_{L_1} : L_1 loss weight; λ_P : Perceptual loss weight; λseg : Dice loss weight; M: Batch size; ω : discriminators parameters; θ : classifier parameters; ζ : generator parameters. 1: for N training iterations do for M batches \mathbf{do} 2: Sample noise: $z \sim p_z$. 3: 4: Sample real images with class: $x, y_1, y_2, c \sim p_{data}$. $\begin{aligned} \tilde{y}_1, \tilde{y}_2 &\leftarrow G_{\theta}(x, z), \tilde{y}_1 \text{ is the synthesized CE-CT}, \ \tilde{y}_2 \text{ is the predicted segment.} \\ \mathcal{L}_D^{(i)} &= log D_{\omega}(x, y_1) + log(1 - D_{\omega}(x, \tilde{y}_1)). \\ \mathcal{L}_C^{(i)} &= BinaryCrossEntropy(C_{\zeta}(t), c). \\ \mathcal{L}_G^{(i)} &= log(1 - D_{\omega}(x, \tilde{y}_1)) + \lambda_{L_1} \|y - \tilde{y}_1\|_1 + \lambda_P \mathcal{L}_{Perceptual}^i + \lambda_C \mathcal{L}_C^i + \lambda_C \mathcal{L}_C^i$ 5:6: 7:8: $\lambda_{seg} \mathcal{L}^i_{seg}(y_2, \tilde{y}_2).$ 9: end for end for $\mathcal{L}_D = \frac{1}{M} \sum_{i=1}^M \mathcal{L}_D^{(i)}$ $\mathcal{L}_C = \frac{1}{M} \sum_{i=1}^M \mathcal{L}_C^{(i)}$ $\mathcal{L}_G = \frac{1}{M} \sum_{i=1}^M \mathcal{L}_G^{(i)}$ 10: 11: 12: $\omega \leftarrow Adam(\nabla_{\omega}\mathcal{L}_D, \alpha, \beta_1, \beta_2)$ 13: $\zeta \leftarrow Adam(\nabla_{\zeta} \mathcal{L}_C, \alpha, \beta_1, \beta_2)$ 14: $\theta \leftarrow Adam(\nabla_{\theta}\mathcal{L}_G, \alpha, \beta_1, \beta_2)$ 15:16: end for