

Supplementary Materials for “EndoDAC: Efficient Adapting Foundation Model for Self-Supervised Depth Estimation from Any Endoscopic Camera”

Table 5. Definition of evaluation metrics.

Metrics Name	Definition
$AbsRel$	$\frac{1}{ \mathbf{D} } \sum_{d \in \mathbf{D}} d^* - d / d^*$
$SqRel$	$\frac{1}{ \mathbf{D} } \sum_{d \in \mathbf{D}} d^* - d ^2 / d^*$
$RMSE$	$\sqrt{\frac{1}{ \mathbf{D} } \sum_{d \in \mathbf{D}} d^* - d ^2}$
$RMSElog$	$\sqrt{\frac{1}{ \mathbf{D} } \sum_{d \in \mathbf{D}} \log d^* - \log d ^2}$
δ	$\frac{1}{ \mathbf{D} } \left \left\{ d \in \mathbf{D} \mid \max\left(\frac{d^*}{d}, \frac{d}{d^*}\right) < 1.25 \right\} \right \times 100\%$

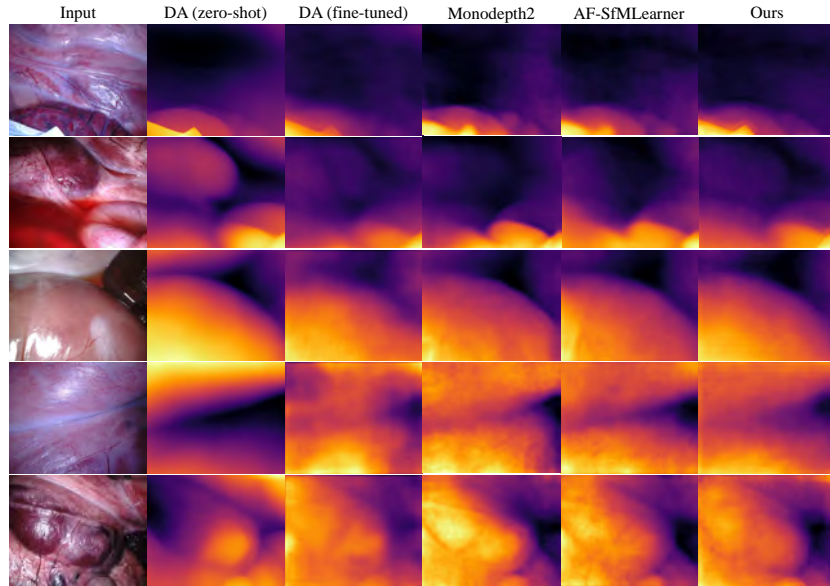


Fig. 4. Qualitative depth comparison on the SCARED dataset.

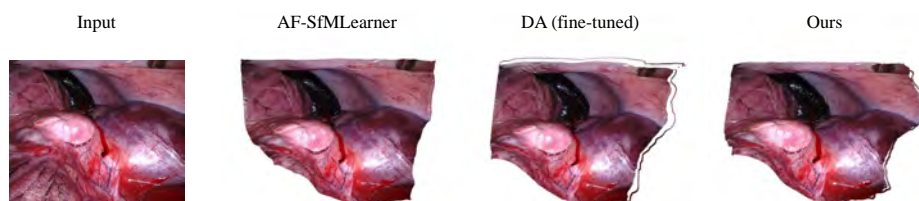


Fig. 5. Qualitative 3D reconstruction comparison on the SCARED dataset.

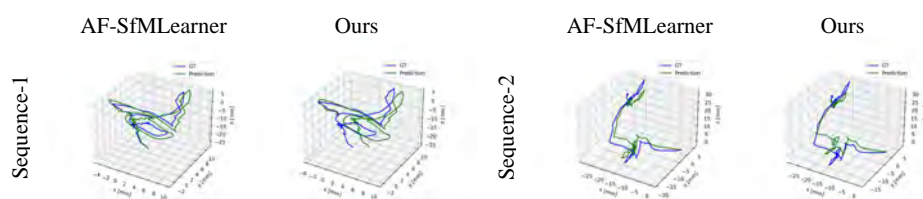


Fig. 6. Qualitative pose estimation comparison on the SCARED dataset.